

NEROXDOMO[®]

PULSE 25 BAT

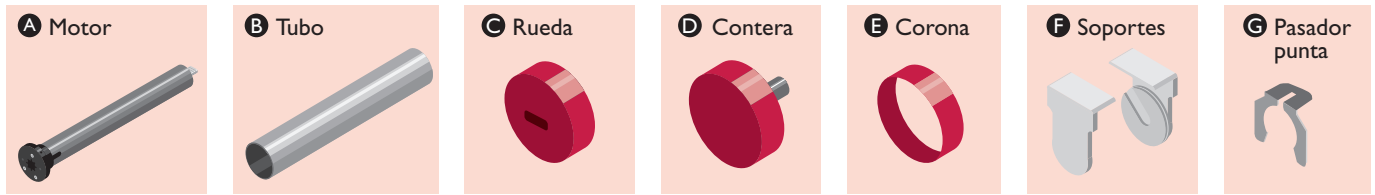
manual de instalación **2** ESP

installation manual **6** ENG

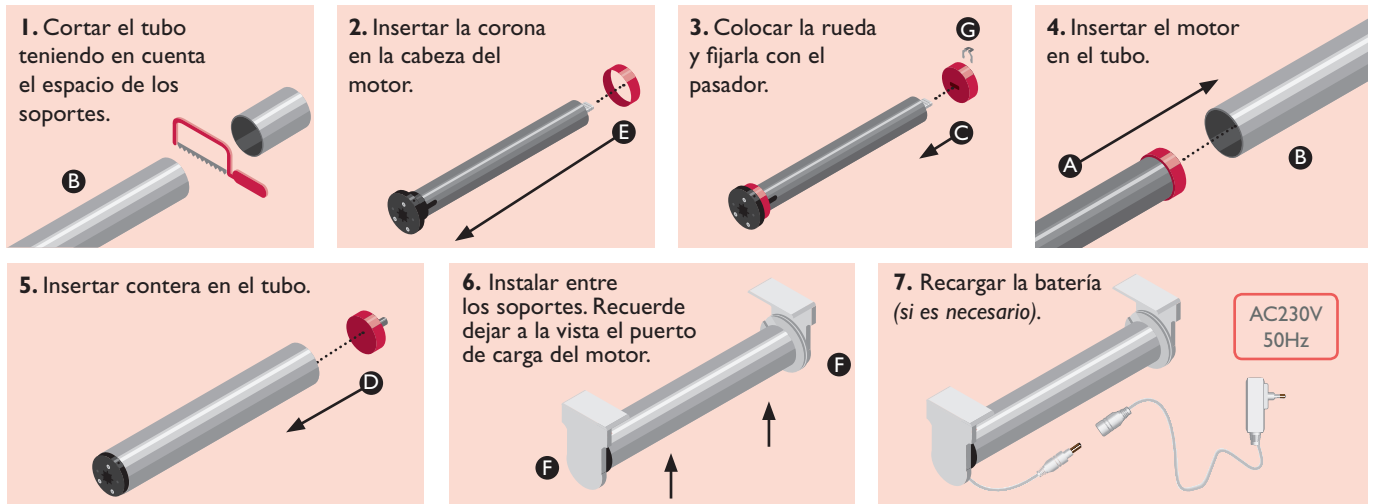


PULSE 25 1/30 BAT 15660000

Componentes



Instalación

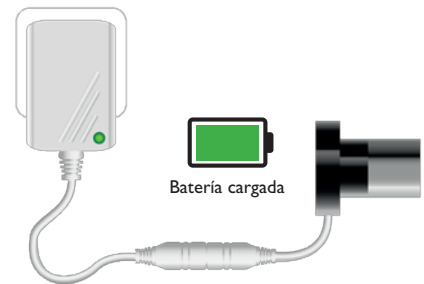
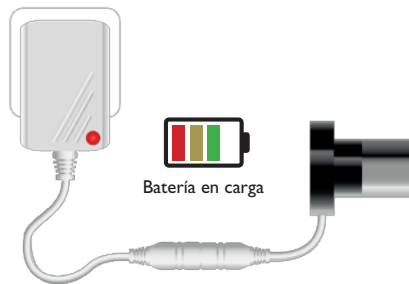


Recarga de batería

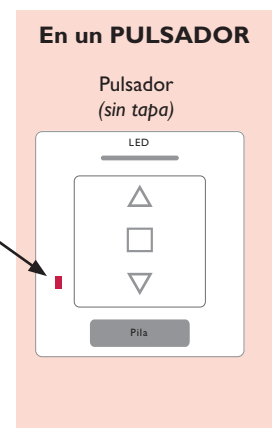
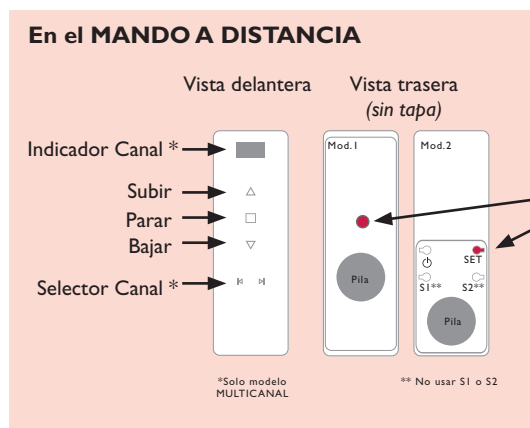
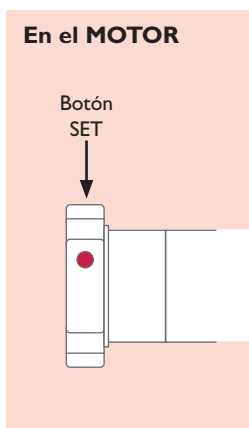
A. Enchufe el cargador a una toma de corriente. Se encenderá la luz verde del cargador.

B. Al conectar el motor se iluminará la luz roja del cargador mientras la carga esté en marcha.

C. Una vez la batería del motor esté completamente cargada el indicador se iluminará en verde.



Botones de programación



Antes de empezar a programar

El motor tiene 2 Finales de Carrera electrónicos y 4 Posiciones Intermedias opcionales programables desde el mando a distancia.

El Primer Final de Carrera se puede definir como Superior o Inferior. La distancia mínima entre Finales de Carrera y Posiciones Intermedias es de 30 cm.

Cuando los 2 Finales de Carrera han sido programados el motor pasa automáticamente a "Modo Continuo".

Las Posiciones Intermedias sólo se pueden añadir cuando los 2 Finales de Carrera han sido programados y únicamente funcionarán en "Modo Continuo".

En "Modo Continuo" al pulsar la tecla ARRIBA/ABAJO del mando a distancia el motor realiza un desplazamiento constante hasta la siguiente Posición Intermedia o Final de Carrera. Si se pulsa 2 veces la tecla ARRIBA/ABAJO el motor no se detendrá en ninguna Posición Intermedia.

En "Modo Pulsos" al pulsar la tecla ARRIBA/ABAJO del mando a distancia el motor realiza un desplazamiento corto. Si se realiza una pulsación larga en la tecla ARRIBA/ABAJO el motor se desplazará continuamente.

Programación básica

⚠ El tiempo entre instrucciones debe ser inferior a 10 segundos o el Motor saldrá del Modo Programación

1. Programación del Mando a distancia / Canal

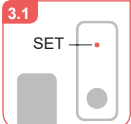

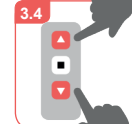
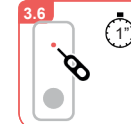

⚠ Si se usa el Mando Multicanal, elegir previamente el canal

				
Pulsar SET durante 1 seg.	El Motor girará ligeramente	Pulsar SUBIR una vez	El Motor girará ligeramente	MANDO / CANAL programado




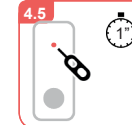


2. Cambio del sentido de giro (solo si es necesario)

				
Pulsar PARAR durante 5 seg.	El Motor girará ligeramente	Pulsar BAJAR una vez	El Motor girará ligeramente	SENTIDO cambiado

3. Programación del 1º Final de Carrera

							
Quitar la tapa del mando para acceder al botón SET	Pulsar SET en el mando durante 1 seg.	El Motor girará ligeramente	Mover hasta la posición deseada	Pulsar SUBIR o BAJAR para seleccionar si el primer final de carrera es el superior o el inferior	Pulsar SET en el mando durante 1 seg.	El Motor girará ligeramente	1ER FINAL DE CARRERA programado

4. Programación del 2º Final de Carrera

						
Mover hasta la posición deseada	Pulsar SET en el mando durante 1 seg.	El Motor girará ligeramente	Pulsar SUBIR o BAJAR para seleccionar si el segundo final de carrera es el superior o el inferior	Pulsar SET en el mando durante 1 seg.	El Motor girará ligeramente	2º FINAL DE CARRERA programado

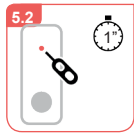
Programación de posiciones intermedias (opcional)

⚠ El tiempo entre instrucciones debe ser inferior a 10 segundos o el Motor saldrá del Modo Programación

5. Programación de Posiciones Intermedias (máximo 4) ⚠ Solo en "Modo Continuo"



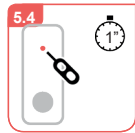
Mover hasta la posición POSICIÓN INTERMEDIA a programar



Pulsar SET en el mando durante 1 seg.



El Motor girará ligeramente



Pulsar SET en el mando durante 1 seg.



El Motor girará ligeramente

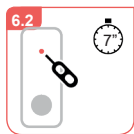


POSICIÓN programada

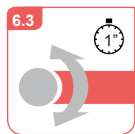
6. Borrado de Posiciones Intermedias (válido también para el 2º Final de Carrera)



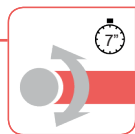
Mover hasta la POSICIÓN INTERMEDIA a eliminar



Pulsar SET en el mando durante 7 seg.



El Motor girará ligeramente pasado 1 seg.



El Motor girará ligeramente pasados 7 seg.



POSICIÓN borrada

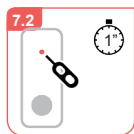
Funciones adicionales

⚠ El tiempo entre instrucciones debe ser inferior a 10 segundos o el Motor saldrá del Modo Programación

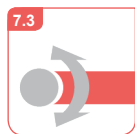
7. Ajuste fino de Final de Carrera / Posición intermedia



Mover hasta el FINAL DE CARRERA o POSICIÓN a ajustar



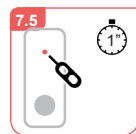
Pulsar SET en el mando durante 1 seg.



El Motor girará ligeramente



Mover hasta alcanzar la nueva posición deseada



Pulsar SET en el mando durante 1 seg.

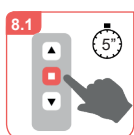


El Motor girará ligeramente



NUEVA POSICIÓN ajustada

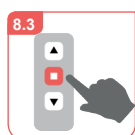
8. Cambio entre "Modo Pulsos" y "Modo Continuo" ⚠ Solo es posible el cambio si los Finales de Carrera están programados



Pulsar PARAR durante 5 seg.



El Motor girará ligeramente



Pulsar PARAR una vez

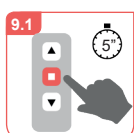


El Motor girará ligeramente



MODO cambiado

9. Añadir Mando a distancia / Canal usando otro programado



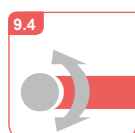
Pulsar PARAR durante 5 seg.



El Motor girará ligeramente



Pulsar SUBIR en el nuevo Mando / Canal

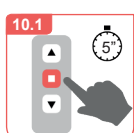


El Motor girará ligeramente

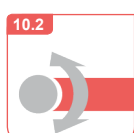


nuevo MANDO A DISTANCIA / CANAL añadido

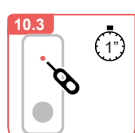
10. Borrado de Mando a distancia / Canal (en Mando Multicanal)



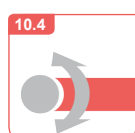
Pulsar PARAR durante 5 seg.



El Motor girará ligeramente



Pulsar SET en el mando durante 1 seg.



El Motor girará ligeramente



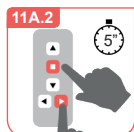
MANDO A DISTANCIA / CANAL borrado

II. Bloqueo / Desbloqueo del número de canales disponibles en mandos multicanal

IIA. Bloqueo de canales



Situarse en el número de canales máximos deseados



Pulsar PARAR y flecha DERECHA durante 5 seg.

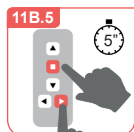


NUMERO DE CANALES bloqueado

IIB. Desbloqueo de canales



Situarse en cualquier canal



Pulsar PARAR y flecha DERECHA durante 5 seg.

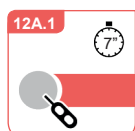


NUMERO DE CANALES desbloqueado

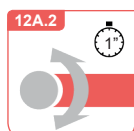
I2. Encendido / apagado del Motor

⚠ El Motor no recibirá señales del Mando a distancia mientras esté apagado. El Motor está encendido si al pulsar el botón SET se ilumina brevemente

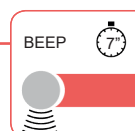
I2A. Apagado del Motor



Pulsar SET durante 7 seg.



El Motor girará ligeramente pasado 1 seg.

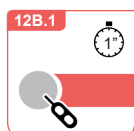


El motor emitirá un pitido largo pasados 7 seg.

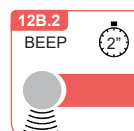


MOTOR apagado

I2B. Encendido del Motor



Pulsar SET durante 1 seg.



El motor emitirá un pitido corto pasados 2 seg.



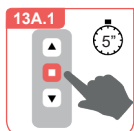
MOTOR encendido

Borrado completo (Reset de fábrica)

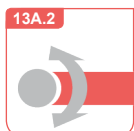
⚠ El tiempo entre instrucciones debe ser inferior a 10 segundos o el Motor saldrá del Modo Programación

⚠ El Borrado Completo eliminará: Posiciones Intermedias, Finales de carrera, Mandos a distancia / Canales, Sentido de giro y Modo seleccionado.

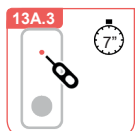
I3A. Borrado completo desde el Mando a distancia



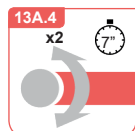
Pulsar PARAR durante 7 seg.



El Motor girará ligeramente



Pulsar SET en el mando durante 7 seg.

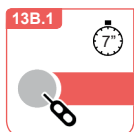


El Motor girará ligeramente 2 veces pasados 7 seg.

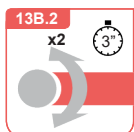


BORRADO COMPLETO realizado

I3B. Borrado completo desde el Motor



Pulsar SET durante 7 seg.



El Motor girará ligeramente 2 veces pasados 3 seg.



BORRADO COMPLETO realizado

Advertencias



Riesgo eléctrico



Riesgo de atrapamiento



No golpear el motor



No perforar el motor



Mantener alejado de líquidos o sustancias corrosivas

Resolución de problemas

Problemas

El motor no funciona o funciona muy despacio.

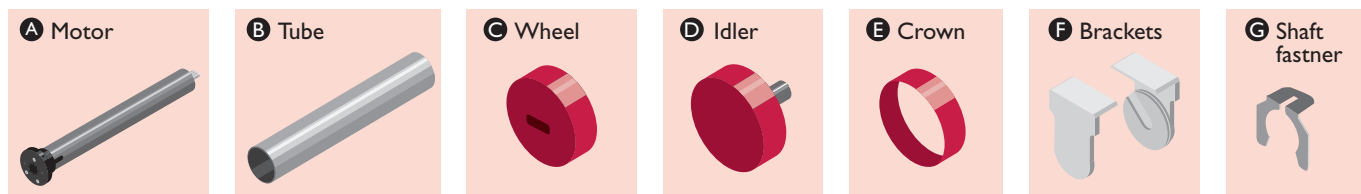
Causas

A - Sobrecarga.
B - Instalación incorrecta.
C - Batería descargada.
D - Motor apagado.
E - El motor alcanzó un Final de Carrera.

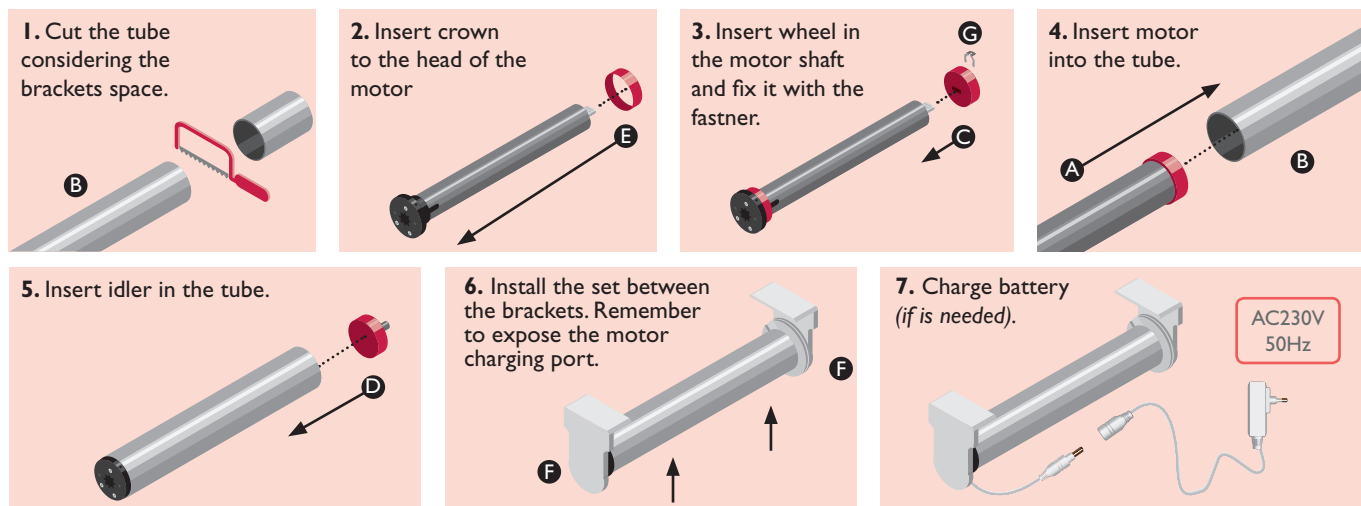
Soluciones

A - Comprobar peso estor.
B - Comprobar componentes.
C - Recargar batería
D - Encender motor.
E - Pulsar sentido contrario.

Components



Assembly

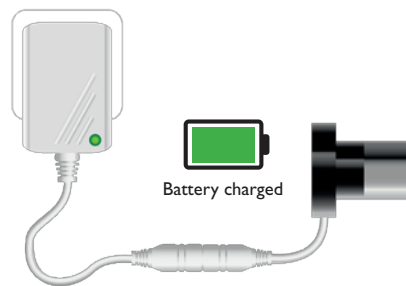
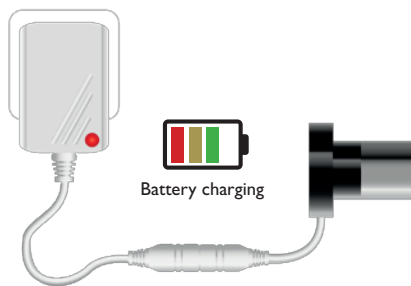


Battery charge

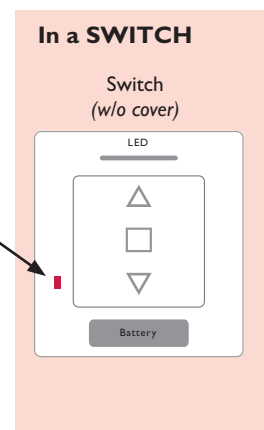
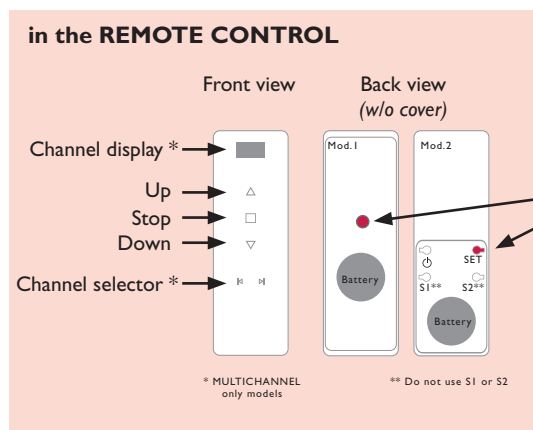
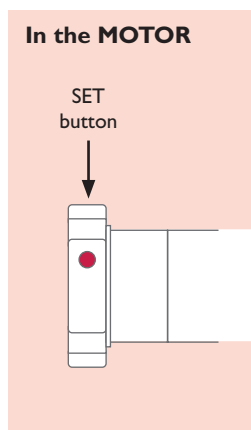
A. Plug the charger into an electrical outlet. Charger green light goes on.

B. Connect the motor to the charger. Charger red light goes on.

C. Battery charged. Charger green light goes on with the motor connected.



Programmation buttons



Before starting...

The motor has 2 electronic Limits and 4 optional Intermediate Positions programmable from remote control.

The First Limit can be defined as Upper or Lower limit.
The minimum distance between Limits and Intermediate Positions is 30 cm.

When the two Limits have been programmed the motor automatically switches to "Continuous Mode".

Intermediate Positions can only be added when the 2 Limits have been programmed and can only be operated in "Continuous Mode".

In "Continuous Mode" when the UP/DOWN button of the remote control is pressed the motor moves constantly until the next Intermediate Position or Limit is reached. If the UP/DOWN button is pressed twice the motor will not stop at any Intermediate Position.

In "Pulse Mode" when the UP/DOWN button of the remote control is pressed the motor moves in short movements. If the UP/DOWN button is long pressed the motor will move continuously.

Basic settings

⚠ The time between operations must be lower than 10 seconds or the motor will leave the setting mode

1. Remote control / Channel setting

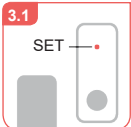
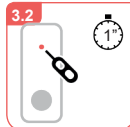

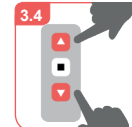

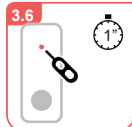


⚠ If a Multichannel Remote control is used, choose the channel first

 Press SET for 1 sec.	 Motor will turn slightly	 Press UP once	 Motor will turn slightly	 REMOTE / CHANNEL added
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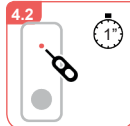
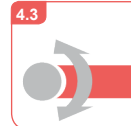


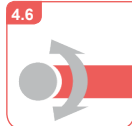

2. Changing turn direction (only if needed)

 Press STOP for 5 sec.	 Motor will turn slightly	 Press DOWN once	 Motor will turn slightly	 TURN DIRECTION changed
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3. Setting 1st limit

 Remove the cover to have access to button SET	 Press SET in RC for 1 sec.	 Motor will turn slightly	 Move until reach the desired height	 Press UP or DOWN to select whether the first limit is the upper or lower limit	 Press SET in RC for 1 sec.	 Motor will turn slightly	 1st LIMIT programmed
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4. Setting 2nd limit

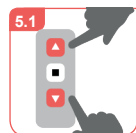
 Move until reach the desired height	 Press SET in RC for 1 sec.	 Motor will turn slightly	 Press UP or DOWN to select whether the second limit is the upper or lower limit	 Press SET in RC for 1 sec.	 Motor will turn slightly	 2nd LIMIT programmed
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Intermediate positions setting (optional)

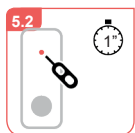
⚠ The time between operations must be lower than 10 seconds or the motor will leave the setting mode

5. Intermediate positions setting (maximum 4)

⚠ Only in "Continuous mode"



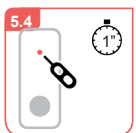
Move to the INTERMEDIATE POSITION desired



Press SET in RC for 1 sec.



Motor will turn slightly



Press SET in RC for 1 sec.

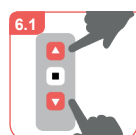


Motor will turn slightly

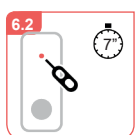


POSITION programmed

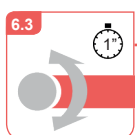
6. Deleting intermediate positions (also valid for 2nd limit)



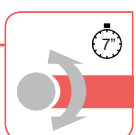
Move to the INTERMEDIATE POSITION you want to delete



Press SET in RC for 7 sec.



Motor will turn slightly after 1 sec.



Motor will turn slightly after 7 sec.



POSITION deleted

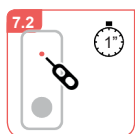
Additional functions

⚠ The time between operations must be lower than 10 seconds or the motor will leave the setting mode

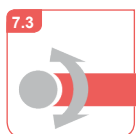
7. Limit / intermediate position fine tuning



Move to the LIMIT or POSITION you want to adjust



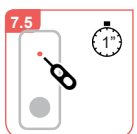
Press SET in RC for 1 sec.



Motor will turn slightly



Move until reach the desired position



Press SET in RC for 1 sec.



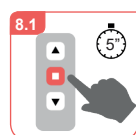
Motor will turn slightly



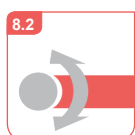
NEW POSITION adjusted

8. Change between "Pulse mode" and "Continuous mode"

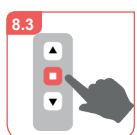
⚠ Only is possible if the Upper and Lower Limits are programmed



Press STOP for 5 sec.



Motor will turn slightly



Press STOP once

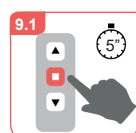


Motor will turn slightly

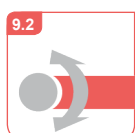


MODE changed

9. Adding a new remote control / channel from one programmed



Press STOP for 5 sec.



Motor will turn slightly



Press UP once in the new REMOTE / CHANNEL

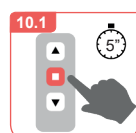


Motor will turn slightly

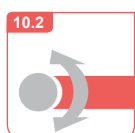


new REMOTE / CHANNEL added

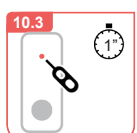
10. Deleting a remote control / channel (in multichannel remote)



Press STOP for 5 sec.



Motor will turn slightly



Press SET in RC for 1 sec.



Motor will turn slightly



REMOTE / CHANNEL deleted

11. Lock / Unlock the quantity of available channels in multichannel remote controls

11A. Lock channels



Choose the number of maximum channels desired



Press STOP and RIGHT arrow for 5 sec.

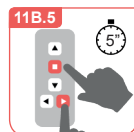


MAX. QUANTITY OF CHANNELS locked

11B. Unlock channels



Select any channel



Press STOP and RIGHT arrow for 5 sec.

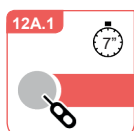


MAX. QUANTITY OF CHANNELS unlocked

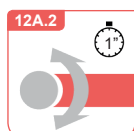
12. Motor turn on / off

⚠ Motor do not receive orders from remotes while it is turned off. The Motor is on if pressing the SET button light briefly.

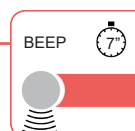
12A. Turn off



Press SET for 7 sec.



Motor will turn slightly after 1 sec.

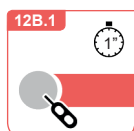


Motor will make a long beep after 7 sec.

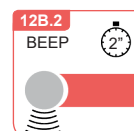


MOTOR off

12B. Turn on



Press SET for 1 sec.



Motor will make a short beep after 2 sec.



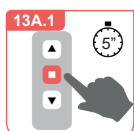
MOTOR on

Factory reset

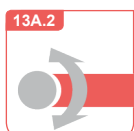
⚠ The time between operations must be lower than 10 seconds or the motor will leave the setting mode

⚠ Factory reset will delete: Intermediate positions, Limits, Remote controls / Channels, Turn direction and Mode selected.

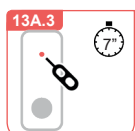
13A. Factory reset from the remote control



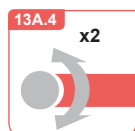
Press STOP for 5 sec.



Motor will turn slightly



Press SET in RC for 7 sec.

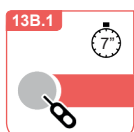


Motor will turn slightly 2 times

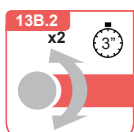


FACTORY RESET done

13B. Factory reset from the motor



Press SET for 7 sec.



Motor will turn twice slightly after 3 sec.



FACTORY RESET done

Warnings

- Electric risk
- Entrapment risk
- Do not hit motor
- Do not drill motor
- Keep away from liquids and corrosive materials

Troubleshooting

Problems

Motor does not work or do it slowly

Causes

- A - Overloading.
- B - Incorrect installation.
- C - Battery discharged.
- D - Motor off.
- E - Motor reached one of the limits.

Solutions

- A - Check weight of the blind.
- B - Check components.
- C - Charge battery.
- D - Turn on motor.
- E - Press opposite direction button.